

# Rustem Ismagilov

Vancouver, BC, Canada

📞 236-880-9699 | ✉ rustem.ismagilov.eng@gmail.com | [in linkedin.com/in/rustem-ismagilov](https://www.linkedin.com/in/rustem-ismagilov)

## Technical Skills

### Mechanical Design

SolidWorks, OnShape, Catia  
GD&T, Fit tolerancing  
DFM, CAM  
FEA: Static, Motion, Thermal

### Fabrication

FDM / Resin 3D printing  
CNC Lathe/Mill: Ti, PEEK  
Laser Cutter, Welder  
Epoxy bonding, Lapping

### Manufacturing

Capacity analysis  
Layout drafting  
Line commissioning  
NC tracking (Pareto, SQL)

### Quality

RCA (FMEA, Fishbone)  
Test Planning & Sustaining  
Inspection (Keyence)  
Technical Documentation

### Hardware

Arduino, soldering  
Controls (PID)  
Python, Matlab  
Oscilloscope, DAQ

## Work experience

### Mechanical Designer

Sanctuary AI

(Full-time) Jan 2026 - Present

(Part time) Oct 2025 – Jan 2026

- **Led hydraulic sealing root cause analysis** - FMEA, Ishikawa, machining, test design, and iteration across 16+ configurations.
- Resolved surface finish, geometry, hardness, and seal dynamics failures - **extending seal life from 10K to 400K+ cycles**
- **Delivered test documentation**, assembly process, and configuration control methodology using **profilometer, internal micrometer, Keyence IM-X, and borescope**, directly informing production RFQ

### Manufacturing Engineer, Co-op

Tesla Inc. – Optimus Actuators manufacturing

Sep 2024 – Aug 2025

- **Designed and built over 60x tools and fixtures** to enable actuator production and **build 50x Teslabots** in time for **We Robot event**.
- **Led the development of manufacturing interfaces** for rotary actuators by coordinating cross-functional meetings with design and integration teams, resulting in **detailed documentation** for automated assembly processes.
- **Identified over 20x DFM improvements** of the rotary actuator to be implemented in next gen actuators to improve its manufacturability.
- **Conducted OEE study and drafted assembly** line layout by capturing 10+ hours of production footage with GoPro.
- Independently **managed the receipt and installation of over 100x workstations** and related equipment within a **1-month** period, meeting key deadlines and preparing the site for the manufacturing team's arrival.
- **Managed a production line for 3 months**, reporting yield performance, testing, and performing **root cause analysis** on top Pareto failures, while maintaining and reissuing line tooling.

### Mechanical Design Engineer, Co-op

Ideon Technologies

(Part-time) Apr - Aug 2024

(Full-time) Sep - Dec 2023

- **Developed Work instructions** and **Quality Control procedures** for production, **facilitating manufacturing outsourcing** in the **US**.
- **Conducted and documented the Process Failure Mode and Effects Analysis (PFMEA)** of the new product.
- **Organized an assembly line** for the fabrication of **muon tomography detectors**.
- **Supervised** a team of **seven technicians**, achieving high **productivity** and **meeting tight deadlines**.
- **Designed, procured** equipment, and **assembled a 600W heat chamber** to perform **Thermal Failure Mode** testing.
- Utilized the designed heat chamber and DAQ system to **identify a thermal fault condition** via **120 hours testing procedure**.

### Mechanical Design Engineer, Co-op

Dometic

Jan - May 2023

- **Organized**, and integrated over **300 requirement clauses** derived from **8 distinct IEC standards** into a comprehensive **testing plan map**.
- **Designed, assembled, and utilized a heat chamber test bench** to test an RV-heater against **12x IEC standards** and prove its compliance.
- **Upgraded the electrical and controls** components of the **pump test bench**, effectively **doubling its throughput** from 5 to 10 pumps, **resulting in 1680 additional hours of runtime**.

### Electrical Research Assistant, Co-op

SFU's Power Electronics and Energy Applications Laboratory

May - Sep 2022

- **Devised a test bench** to validate the accuracy of **Zubieta's model** on a single **BCAP3000 supercapacitor**.
- **Designed** a custom **PCB** circuit in **Altium** to amplify the over-shunt signal read by the **DAQ** system.

## Education and Student Clubs

**Simon Fraser University:** BAsC - Mechatronics Systems Engineering **CGPA = 3.76**

Sep 2019 – Dec 2025

**Thrust Vector Control Team lead** - SFU Rocketry club

Feb – Aug 2024

- **Founded and led TVC subteam** - team structure, weekly meetings, and accountability across 5 engineers over 5 months
- **Delivered first TVC module design, BOM, drawings, Simulink simulation, and hardware approach** for a 25kN bipropellant rocket.
- Recognized as **fastest and most productive subteam** by club leadership, contributing to the **\$30K DarkVision award-winning presentation**.